

ABSTRACT

A manipulator for a mobile object which allows operating the mobile object with a natural feeling without difficulty irrespective of 5 the physical condition of the user, and a push cart and a walker including such a manipulator are to be provided. The straight travel reference vector F_s , direction change reference vector F_c and rotating reference vector F_r are developed in advance based on the applied manipulating force of the user. An angle defined by the 10 vector of the manipulating force applied by the user (applied manipulating force vector F_i) and the straight travel reference vector F_s is denoted as α , an angle defined by the applied manipulating force vector F_i and the direction change reference vector F_c as β , and an angle defined by the applied manipulating 15 force vector F_i and the rotating reference vector F_r as γ . Herein the angles are illustrated as $\alpha < \beta < \gamma$, and the moving mode (straight travel mode in this example) is selected in relation with the reference manipulating force vector (the straight travel reference vector F_s in this example) that makes the smallest angle (α).